

| • | cifications |
|--|--------------------------------|
| General specifications | |
| Total weight (W/A batteries) | 15.4 kg |
| Max. take-off weight | 29 kg |
| Dimensions | 1460 x 1020 x 610 [mm] |
| Max. hovering time | 26 min (18 kg) 12.5min (29 kg) |
| GPS | GPS, GLONASS, Galileo |
| Hovering precision | ±10 cm (RTK) ±2m (without RTK) |
| Rotor dimensions | 30 x 9 |
| Motor dimensions | 81 x 20 mm |
| Motor KV value | 100 KV |
| Battery capacity | 16000 mAh |
| Battery voltage | 44.4V |
| Battery weight | 4.7 kg |
| Spraying | |
| Per Hectare Performance | 10 ha/h |
| Spraying system | CDA |
| Number of Nozzles | 2 |
| Droplet size | 40 - 1000 μm |
| Adjustable droplet size | ✓ |
| Drift | LOW risk |
| Adjustable working width | 1.5 - 6 m |
| Spot spraying | ✓ |
| Pump type | Membrane |
| Maximum flow | 5L/min |
| Pump operating voltage | 48V |
| Execution of work | • |
| Technology developed for European Agricultural conditions | ✓ |
| IP protection | IP54 |
| Easy transportability | ✓ |
| Modular payload attachability | ✓ |
| Obstacle avoidance | RTK-based |
| FPV camera | Front - rear |
| Battery charging time | ~11 min |
| Effective signal range of RC | ~8 km |
| Altitude measurement | LIDAR |
| Flight planning | <u>'</u> |
| Software source code | Open |
| Flight plan creation on a pc | ✓ |
| Handling of SHP and KML files | SHP and KML |
| Software compatibility | ✓ |
| Downward facing camera for obstacle selection | ✓ |
| RTK base in the package | ✓ |
| Data security | ✓ |
| No data transmission to remote servers | ✓ |
| Flight | • |
| Max. pitch anglec | 30° |
| Max. operating flight speed | 7 m/s |
| Max. level speed | 24 m/s |
| Max. flight altitude | 120 m |
| | + |